# CS5460: Operating Systems

### Lecture 3: OS Organization

(Chapters 2-3)



### Last Time

#### Generic computer architecture

- Lots of pieces
- OS has to manage all of them

#### Processor modes

- OS executes with the CPU in kernel mode
- User programs execute with the CPU in user mode
- Kernel mode code is trusted if it is bad, the whole OS is bad

#### Main OS Goal: Provide the "process model"

- Dynamically created virtual address spaces + virtual CPUs
- Processes are isolated by default
- System call mechanism pokes a hole in the firewall



### Last Time Continued

- What are the 4 basic ways in which the processor can start executing in kernel mode?
  - Boot
  - System call
  - Other trap
  - Interrupt



# Anatomy of a System Call

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- User apps make system calls to execute privileged instructions
- Anatomy of a system call:
  - Program puts syscall params in registers
  - Program executes a trap:
    - » Minimal processor state (PC, PSW) pushed on stack
    - » CPU switches mode to KERNEL
    - » CPU vectors to registered trap handler in the OS kernel
  - Trap handler uses param to jump to desired handler (e.g., fork, exec, open, ...)
  - When complete, reverse operation
    - » Place return code in register
    - » Return from exception





# Last Time Continued

#### System call

- Arguments passed in registers
- Return code passed in register
- Usually, there are side effects in kernel state or process's memory
- Should operate correctly for all possible inputs
  - » Why?
  - » How would you test this?
- Should be semantically simple



Today

- More traps
- Device I/O
- Interrupts
- Introduction to processes
  - What are they?
  - Where do they come from?
  - How do they relate to I/O?
- The process abstraction and how it is built is one of the main topics of this class
  - Every user program runs inside a process
  - Every system call comes from some process
  - The kernel is not a process



### Traps

#### • Architecture detects special events:

- trap request syscall, int
- read or write invalid memory access
- divide by zero
- privileged instruction by user mode code
- ...

#### • When processor detects condition:

- Save minimal CPU state (PC, sp, ...) done by hardware
- Switches to KERNEL mode
- Transfers control to trap handler
  - » Indexes trap table w/ trap number
  - » Jumps to address in trap table (\*)
  - » Handler saves more state and may disable interrupts
- RTE/IRET instruction reverses operation



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# 0x0082404

0x0082000

. . .

**TRAP VECTOR:** 

Illegal address Mem Violation Illegal instruction System call

Here, 0x82404 is address of		
handle_illeg	gal_addr().	

# Controlling I/O Devices

#### Hardware is controlled using device registers

- CPU can read/write device registers
- Device drivers read/write registers to control device
  - » Memory-mapped I/O: registers mapped to special addresses
  - » Programmed I/O: special instructions to read/write registers
- Registers may look like memory but they don't act like it!

### • DMA: <u>Direct Memory Access</u>

- Modern I/O devices can directly read/write system memory
- OS manages "DMA channels" to control memory device can access

### Device signaling: Polling vs Interrupts

- Polling: OS "polls" devices to see if they need attention
- Interrupts: Devices signal OS when they need attention



# **Polling and Interrupts**

#### • I/O is concurrent with main processor

- CPU initiates I/O with I/O register writes
- CPU detects I/O completion/signal via:
  - » Interrupt (async hardware signal)
  - » Polling (loop reading I/O register)
- Question: Polling vs interrupts when?

#### Interrupt raises signal on CPU pin

- Each device configured to use a particular interrupt number
- Usually, CPU "traps" to the appropriate interrupt handler next cycle
- Can selectively mask interrupts (not traps!)

#### Interrupts can cost performance

- Flush CPU pipeline + cache/TLB misses
- Handlers often need to disable interrupt



#### **INTERUPT VECTOR:**

_		-
	0x008c408	Clock
ſ	0x0088044	Disk
ſ	0x008317c	Mouse
ſ	0x0089f0c	Keyboard
ſ		

### **Issues with Interrupts**

#### Interrupt overload

- Some devices can generate interrupts faster than CPU can handle
- Example: "receiver livelock" in high speed networks
- Solution: buffering, adapt between polling and interrupts
- Interrupts on PCs go through external interrupt controller
  - Can be many sources of interrupts
  - Interrupt may be shared between devices
    - » Question: How can this be done?!?
  - Embedded CPUs often have much nicer interrupt subsystems than PCs do



# **Issues with Interrupts**

- What stack do interrupts use?
- What process is running when an interrupt arrives?

#### Good manners for interrupt handlers:

- When invoked, perform all work associated with device
- Do not disable interrupts very long (e.g., up to 100usec)

### Interrupts can be very hard to get right

- Concurrency is hard
- Standard debugging techniques may not work



# **Initializing Traps/Interrupts**

#### Vectors pinned at known physical addresses

Location specified by CPU vendor or configurable w/ register

### Initialized (carefully!) during boot process

```
// interrupts disabled on boot
...
intr_vector[0] = (void *) handle_clock_int;
intr_vector[1] = (void *) handle_disk_int;
...
enable_interrupts();
void handle_clock_int() { ... };
```



### Traps vs Interrupts

#### • Traps are synchronous

- Generated inside the processor due to instruction being executed
- Instructions may
  - » Always trap example?
  - » Sometimes trap example?
  - » Never trap example?
- Cannot be masked
- System calls are one kind of trap
- Interrupts are asynchronous
  - Generated outside the processor
  - Can be masked





#### • System calls:

- Arguments places in well-known registers
- Perform trap instruction  $\rightarrow$  vector to system call handler
  - » Low level code carefully saves cpu state
  - » Processor switches to protected/kernel mode
  - » Syscall handler checks param and jumps to desired handler

#### - Return from system call

- » Result placed in register and low level code restores state
- » Perform "rte" instruction: switches to user mode and returns to location where "trap" was called

### OS manages trap/interrupt tables

- Controls the "entry points" in the kernel  $\rightarrow$  secure
- Traps are synchronous; interrupts are asynchronous



# Intro to Processes

How are OS and I/O protected from user processes?

### Spatial protection

- Memory protection: OS and I/O registers mapped into protect memory (supervisor-only)
- Privileged instructions: User processes may not be allowed to perform I/O ops
- Temporal protection
  - Timer interrupts keep user processes from hogging CPU
- Traps allow user processes to break through protection barrier:
  - <u>BUT</u> OS controls entry points into kernel
  - Most system calls vectored to a single system call handler
    - » Parameter to system call specifies what operation desired



# What's a Process?

- Process: execution context of running program
- A process does not equal a program!
  - Process is an *instance* of a program
  - Many copies of same program can be running at same time
- OS manages a variety of activities
  - User programs – System programs (e.g., print spool,
  - Batch jobs and scripts
- file server, network daemons, ...)
- Each of these activities is encapsulated in a process
- Everything that happens is either in the OS or in a process
  - Again, the OS is not a process



### **Process Management**

- OS manages processes:
  - OS creates, deletes, suspends, and resumes processes
  - OS schedules processes to manage CPU allocation ("scheduling")
  - OS manages inter-process communication and synchronization
  - OS allocates resources to processes (and takes them away)

#### Processes use OS functionality to cooperate

- Signals, sockets, pipes, files to communicate
- Synchronization for resources modified by multiple processes



### What's in a Process?



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# **Practical Process Management**

### • On a Unix machine, try:

- ps -Af : lots of info on all running processes
- kill -9 547 : immediately terminates process with PID 547
- top : displays dynamic info on top running jobs
- Write a program that calls:
  - » getpid(): returns current process' s PID
  - » fork(): create a new process
  - » exec(): load a new program into the current process

### Similar commands work on Mac OS X (BSD Unix!)

On Windows → Task manager (CTL-ALT-DEL)



# **Processes and Interrupt-Driven IO**

What you see is:



#### What the OS sees is:

- 1. Cursor control process blocked on mouse device (e.g., /dev/cua0)
- 2. User moves mouse
- 3. Mouse hardware generates interrupt
- If interrupts on, CPU saves state and jumps to handle\_mouse\_int()
- 5. handle\_mouse\_int() pushes some registers on stack, reads position delta from mouse controller
- 6. handle\_mouse\_int() checks to see if a process is waiting on device

- 7. handle\_mouse\_int() asks OS to wake up cursor-control process and returns
- 8. CPU scheduler evaluates priority of runnable processes:
  - Is cursor control process higher?
  - If so, switch to cursor control proc
- 9. Cursor control process computes new mouse position, sends cmd to video driver to update screen
- **10.** Video driver updates screen
- 11. Cursor control process goes to sleep (assuming no new movement)



# **Important From Today**

- Trap (synchronous)
- Interrupt (asynchronous)

### Interaction with devices through

- Device registers
- Interrupts
- DMA

#### Processes

- This is a big part operating system's job
- This is a big part of this class
- Every system call comes from some process
- Boot sequence
- Flow of control when a process does I/O

