

LES of Turbulent Flows: Lecture 1 Supplement (ME EN 7960-003)

Prof. Rob Stoll
Department of Mechanical Engineering
University of Utah

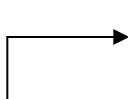
Fall 2014

Statistical Tools for Turbulent Flow

- A consequence of the random behavior of turbulence and the fact that its histogram appears to be reproducible is that turbulence is usually studied from a statistical viewpoint.

Probability:

$$P = P(B) = P\{U < V_b\} \quad \text{for event } B \equiv \{U < V_b\}$$


 Some event (value) V_b in the space V (e.g., our sample velocity field)

this is the probability (likely-hood) that U is less than V_b where $P=0$ means there is no chance and $P=1$ means we have certainty.

Cumulative density function (cdf):

$$F(V) \equiv P\{U < V\} \quad \text{where for a specific event } P(B) = P\{U < V_b\} = F(V_b)$$

$$\text{and if we have } P(C) \equiv P\{V_a \leq U < V_b\} = F(V_b) - F(V_a)$$

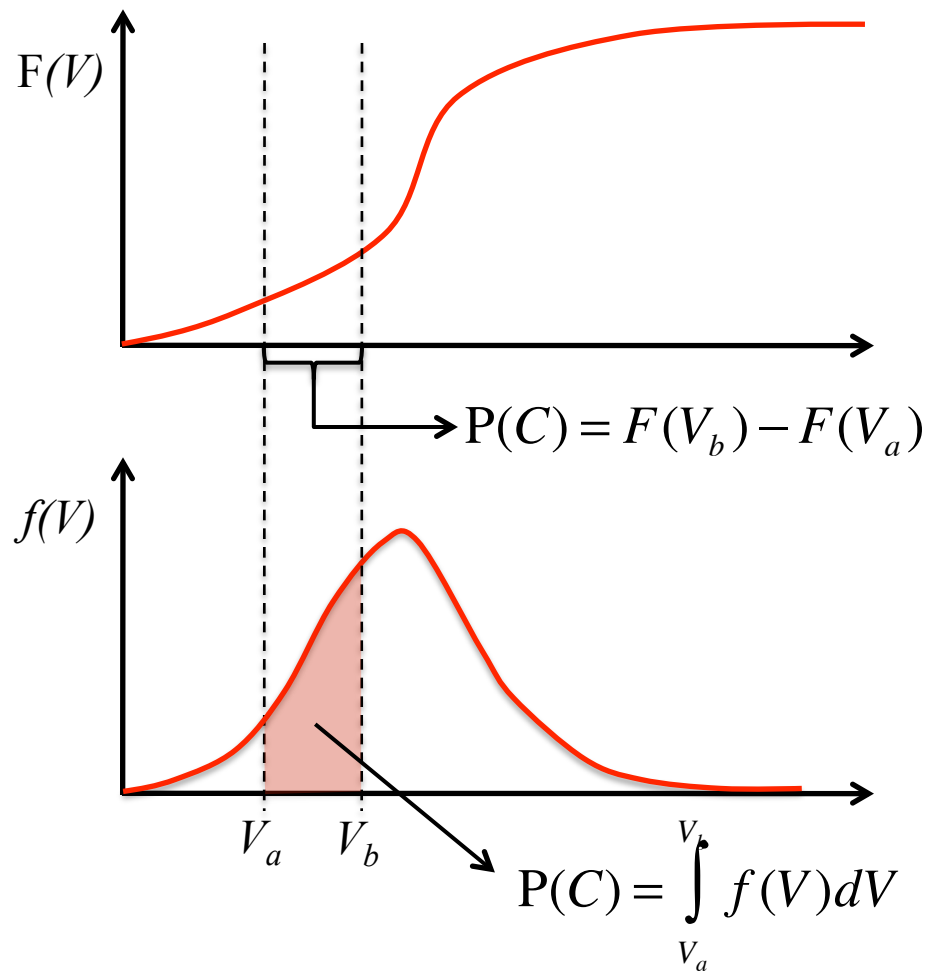
this is bounded by: $F(-\infty) = 0$ ($U < -\infty$ is impossible)

$$F(\infty) = 1 \quad (U < \infty \text{ is certain})$$

We also know that since P is non negative, F is non a non decreasing function

Statistical Tools for Turbulent Flow

pdf vs cdf



Means and Moments

- The pdf fully defines the statistics of a signal (random variable)
- If two signals have the same pdf, they are considered to be statistically identical
- We can also define a signal by its individual stats that collectively describe the pdf

- The mean (or expected value)

$$\langle U \rangle \equiv \int_{-\infty}^{\infty} V f(V) dV \text{ in a discrete form we have } \frac{1}{N} \sum_{i=1}^N V_i$$

- The mean is the probability weighted sum of all possible values
- In general for and $Q(U) \rightarrow$ something that is a function of U

$$\langle Q(U) \rangle \equiv \int_{-\infty}^{\infty} Q(V) f(V) dV$$

and from this equation we can show that for constants a and b :

$$\langle aQ(U) + bR(U) \rangle = a\langle Q(U) \rangle + b\langle R(U) \rangle$$

Means and Moments

- We can also define a fluctuation from the mean by

$$u \equiv U - \langle U \rangle$$

- The variance is then the mean square fluctuation

$$\sigma_u^2 = \text{var}(U) = \langle u^2 \rangle \equiv \int_{-\infty}^{\infty} (V - \langle U \rangle)^2 f(V) dV \quad \text{discretely} \quad \sigma_u^2 = \frac{1}{N-1} \sum_{i=1}^N (V_i - \langle U \rangle)^2$$

- And the standard deviation (or rms) is simply the root of the variance

$$\sigma_u = \text{sdev}(U) = \langle u^2 \rangle^{1/2}$$

- We can define the n^{th} central moment as:

$$\mu_n \equiv \langle u^n \rangle = \int_{-\infty}^{\infty} (V - \langle U \rangle)^n f(V) dV$$

- Many times we prefer to express variables as standardized random variables

$$\hat{U} \equiv \frac{U - \langle U \rangle}{\sigma_u} \quad \text{a centered and scaled variable}$$

- The standardized moments are then

$$\hat{\mu}_n \equiv \frac{\mu_n}{\sigma_u^n} = \int_{-\infty}^{\infty} \hat{V}^n \hat{f}(\hat{V}) d\hat{V} \quad \text{with } \hat{\mu}_0 = 1, \hat{\mu}_1 = 0 \text{ and } \hat{\mu}_2 = 1$$

Means and Moments

- The different moments each describe an aspect of the shape of the pdf

$\mu_1 \Rightarrow$ mean or expected value

$\mu_2 \Rightarrow$ variance

$\mu_3 \Rightarrow$ skewness

$\mu_4 \Rightarrow$ kurtosis (or flatness)

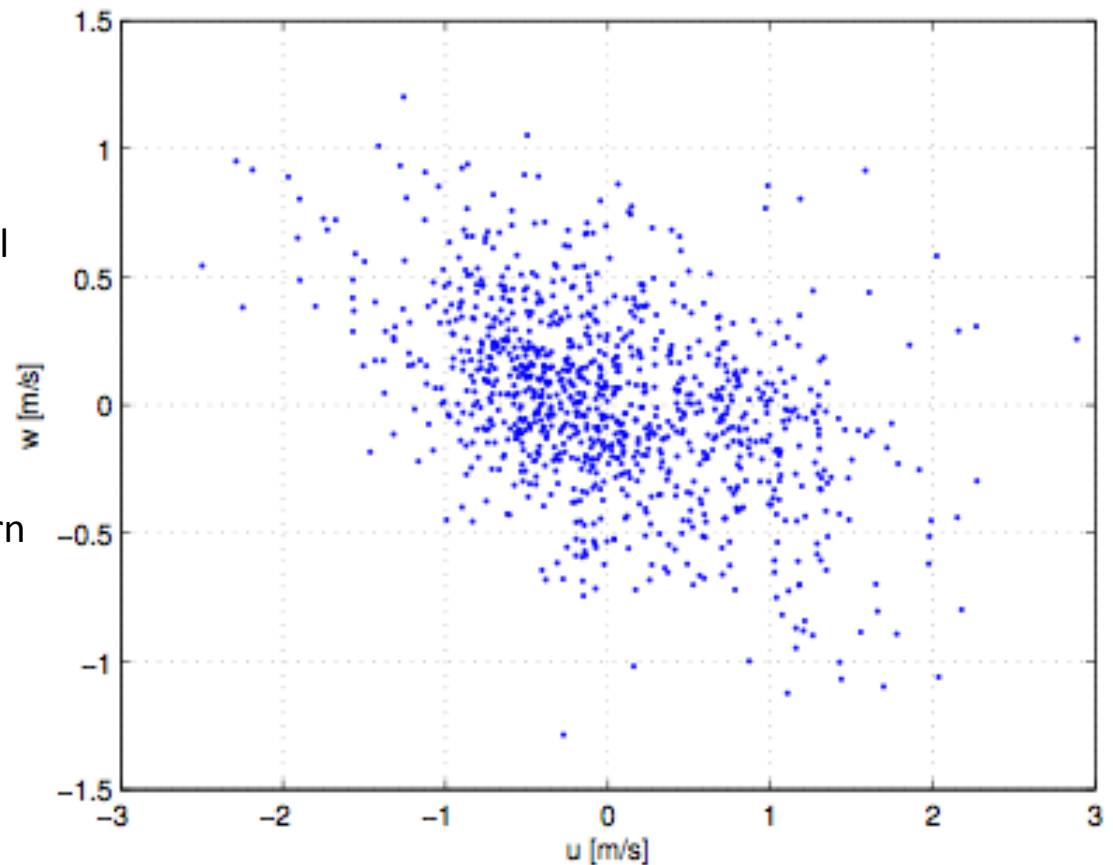
- In basic probability theory we have several different types of pdfs. Pope 3.3 gives a fairly extensive list of these the most important of which is the normal or Gaussian distribution

Joint Random Variables

- So far the description has been limited to single Random variables but turbulence is governed by the Navier-Stokes equations which are a set of 3 coupled PDEs.
- We expect this will result in some correlation between different velocity components

- Example, turbulence data from the ABL: scatter plot of horizontal (u) and vertical (w) velocity fluctuations.

- The plot appears to have a pattern (negative slope)



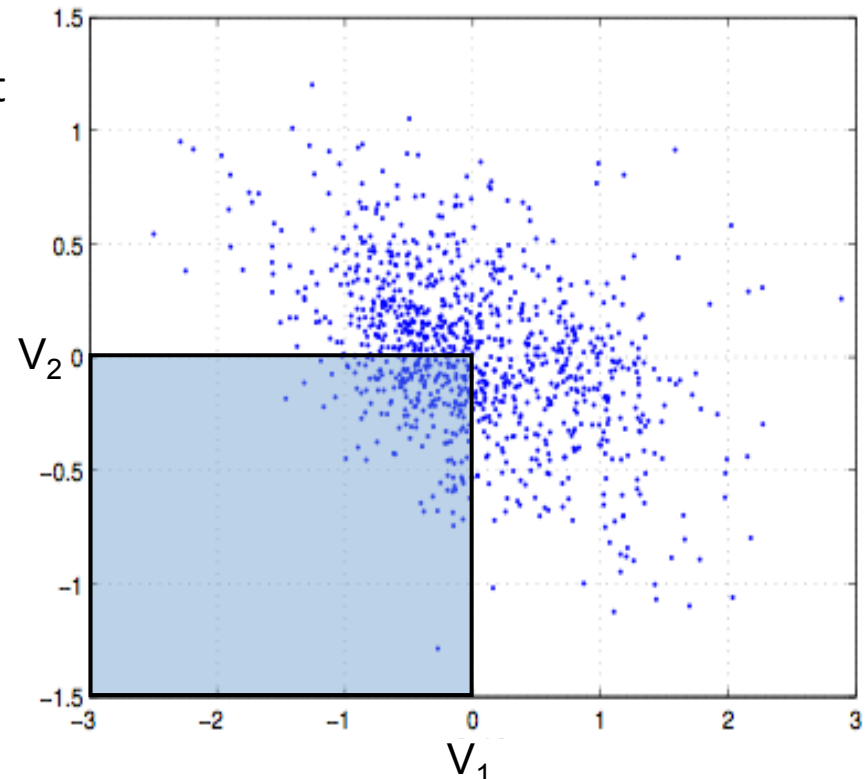
Joint Random Variables

- Joint Cumulative Density Function (joint CDF):

$$F_{12}(V_1, V_2) \equiv P\{U_1 < V_1, U_2 < V_2\}$$

Sample space of our
random variables U_1 and U_2

- In the figure, the CDF is the probability that the variable (U_1 and U_2) lie within the shaded region
- The joint CDF has the following properties:
 - It is non decreasing
 - $F_{12}(-\infty, V_2) = P\{U_1 < -\infty, U_2 < V_2\} = 0$
 - $F_{12}(\infty, V_2) = P\{U_1 < \infty, U_2 < V_2\} = P\{U_2 < V_2\} = F_2(V_2)$
i.e. since $U_1 < \infty$ is certain, the joint cdf = the single variable cdf



Joint PDF

- The **joint PDF** is given by:

$$f_{12}(V_1, V_2) = \frac{\partial^2}{\partial V_1 \partial V_2} F_{12}(V_1, V_2)$$

- Similar to the single variable PDF, if we integrate over V_1 and V_2 we get the probability

$$P\{V_{1a} \leq U_1 < V_{1b}, V_{2a} \leq U_2 < V_{2b}\} = \int_{V_{1a}}^{V_{1b}} \int_{V_{2a}}^{V_{2b}} f_{12}(V_1, V_2) dV_2 dV_1$$

- The joint PDF has the following properties:

- $f_{12}(V_1, V_2) \geq 0$

- $f_2(V_2) = \int_{-\infty}^{\infty} f_{12}(V_1, V_2) dV_1 \Rightarrow$ the marginal PDF of U_2

- $\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{12}(V_1, V_2) dV_1 dV_2 = 1$

- Similar to a single variable, if we have $Q(U_1, U_2)$ then

$$\langle Q(U_1, U_2) \rangle = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} Q(V_1, V_2) f_{12}(V_1, V_2) dV_2 dV_1$$

- With this idea we can give a rigorous definition for a few important stats (next)

Important single point stats for joint variables

- **covariance:**

$$\text{cov}(U_1, U_2) = \langle u_1 u_2 \rangle = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (V_1 - \langle U_1 \rangle)(V_2 - \langle U_2 \rangle) f_{12}(V_1, V_2) dV_2 dV_1$$

- Or for discrete data

$$\text{cov}(U_1, U_2) = \langle u_1 u_2 \rangle = \frac{1}{N-1} \sum_{j=1}^N (V_{1j} - \langle U_1 \rangle)(V_{2j} - \langle U_2 \rangle)$$

- We can also define the correlation coefficient (non dimensional)

$$\rho_{12} = \frac{\langle u_1 u_2 \rangle}{[\langle u_1^2 \rangle \langle u_2^2 \rangle]^{1/2}}$$

- Note that $-1 \leq \rho_{12} \leq 1$ and negative value mean the variables are anti-correlated with positive values indicating a correlation
- **Practically speaking**, we find the PDF of a time (or space) series by:
 1. Create a histogram of the series (group values into bins)
 2. Normalize the bin weights by the total # of points

Two-point statistical measures

- **autocovariance:** measures how a variable changes (or the correlation) with different lags

$$R(s) \equiv \langle u(t)u(t+s) \rangle$$

- or the autocorrelation function

$$\rho(s) \equiv \langle u(t)u(t+s) \rangle / \langle u(t)^2 \rangle$$

- These are very similar to the covariance and correlation coefficient
 - The difference is that we are now looking at the linear correlation of a signal with itself but at two different times (or spatial points), i.e. we lag the series.

- Discrete form of autocorrelation:

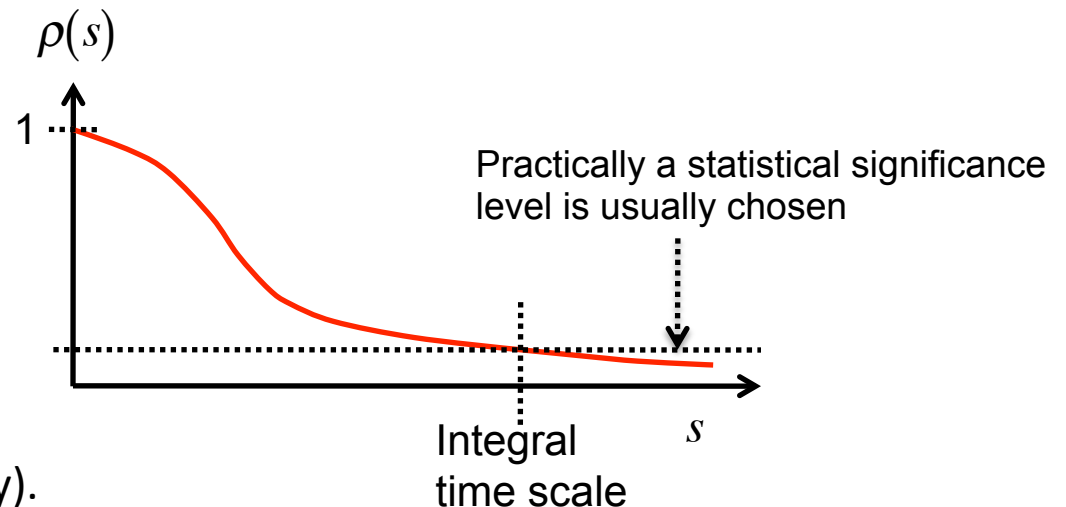
$$\rho(s_j) = \frac{\sum_{k=0}^{N-j-1} (u_k u_{k+j})}{\sum_{k=0}^{N-1} (u_k^2)}$$

- We could also look at the cross correlations in the same manner (between two different variables with a lag).
- Note that: $\rho(0) = 1$ and $|\rho(s)| \leq 1$

Two-point statistical measures

- In turbulent flows, we expect the correlation to diminish with increasing time (or distance) between points:

- We can use this to define an Integral time scale (or space). It is defined as the time lag where the integral $\int_0^{\infty} \rho(s) ds$ converges. and can be used to define the largest scales of motion (statistically).



- Another important 2 point statistic is the **structure function**:

$$D_n(r) \equiv \left\langle [U_1(x+r, t) - U_1(x, t)]^n \right\rangle$$

This gives us the average difference between two points separated by a distance r raised to a power n . In some sense it is a measure of the moments of the velocity increment PDF. Note the difference between this and the **autocorrelation which is statistical linear correlation** (ie multiplication) of the two points.